

**Justness:
when progress is too weak
and fairness it too strong**

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Motivation



- verification of/reasoning about *safety* properties
 - many applications
 - routing protocols
 - mutual exclusion
 - garbage collection

 - “easy” to achieve
 - at least we know what to do
 - existence of solid theoretical foundations
 - rely guarantee/Owicki-Gries/(concurrent) separation logic
 - standard techniques relate (labelled) transition systems
simulation, bisimulation, refinement, ...

Motivation



- examples

- Garbage Collection

- “No memory is deleted that still used”

- the program **skip** satisfies the safety property

- Mutual Exclusion Protocols

- “Critical Section is not accessed by more than one process at a time”

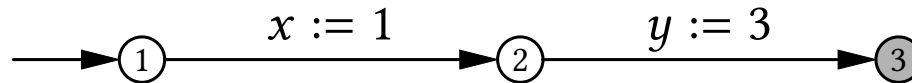
- the program that does not allow any process to enter the critical section satisfies the safety property

- Liveness is as important as Safety

Liveness by Example

- does the following program satisfy $\mathbf{AF}(y = 3)$

$x := 1; y := 3$



Progress



a (transition) system in a state that admits an outgoing (non-blocking) transition will eventually progress, i.e., perform a transition

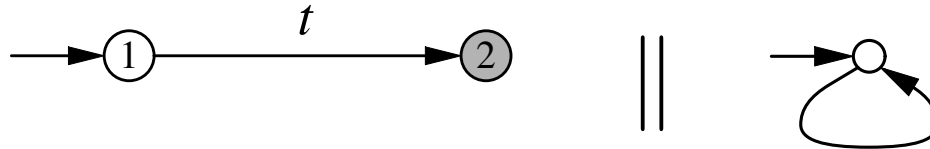
- assumes that no process gets stuck in a state with outgoing transitions
- progress is widely applied (often implicitly, e.g. CCS)
- Misra calls it “minimal progress”

- assumes also that atomic actions always terminate

- generalised to non-blocking actions;
a non-blocking action cannot be blocked by the environment
(assignment, I drinking a beer, ...)

Progress is Too Weak

- assume the following independent programs



- does $\mathbf{AF}(@2)$ hold (under the assumption of progress)?
- progress is too weak
- progress is not compositional

Completeness Criterion



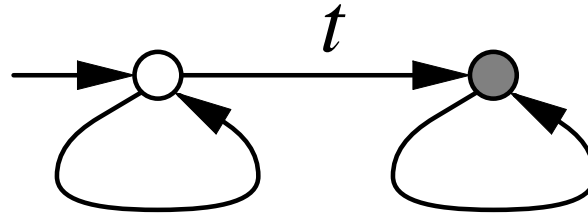
- progress (and other fairness assumptions) rule out paths in a transition system
- progress rules out “incomplete” paths

- completeness criterion F is stronger than H if it rules out at least at least all paths that are ruled out by H

- to verify liveness properties we need something stronger than progress (this is well known)

Weak and Strong Fairness

- $\mathbf{AF}(@2)$ does not hold



- the standard solution is to add a stronger completion criterion:
weak/strong fairness

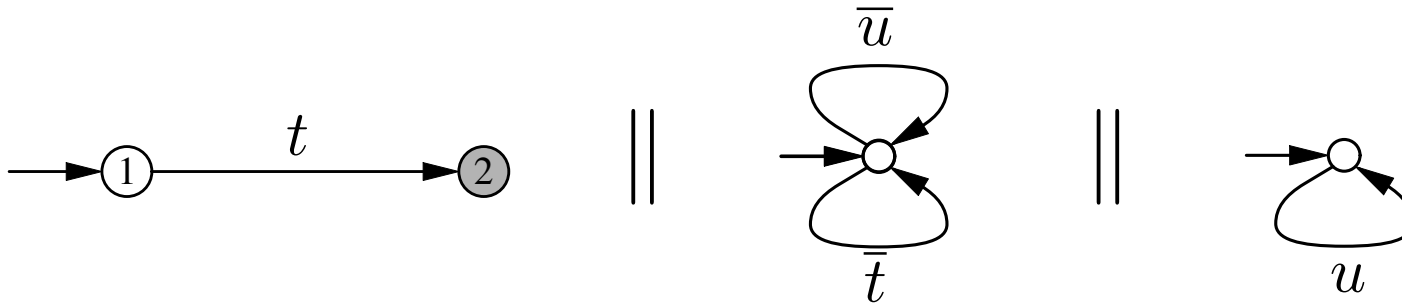
weak fairness: If a task, from some point onwards, is perpetually enabled (meaning in each state) it will eventually be scheduled

strong fairness: If a task is enabled infinitely often, but allowing interruptions during which it is not enabled, it will eventually be scheduled.

- both fairness assumptions guarantee the liveness property

Fairness is Too Strong

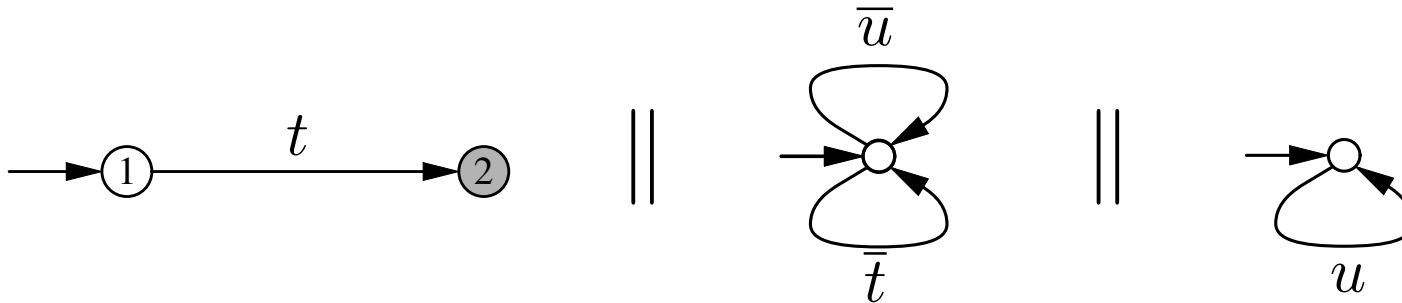
- Another example; adding synchronisation



- you go to a bar, are you guaranteed to get a drink
- weak/strong fairness says “yes”,
but what if the bartender does not like you

Fairness is Too Strong

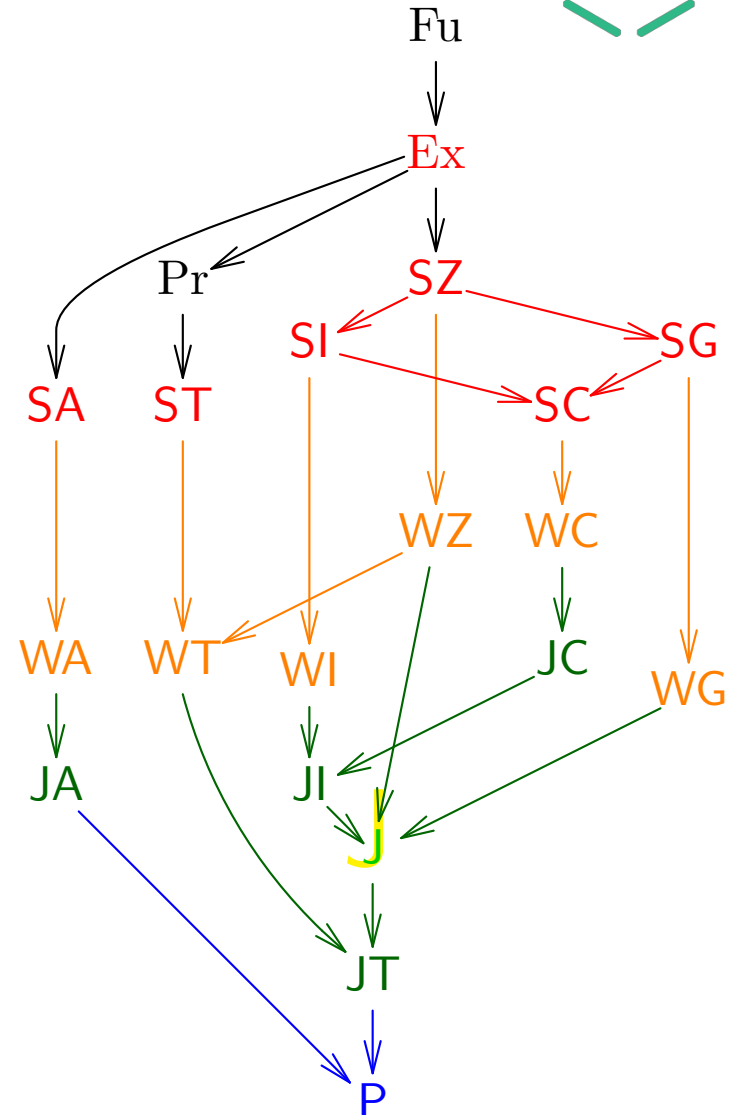
- let the central component be a mutual exclusion protocol



- adding fairness seems counter-intuitive

But there are other notions of fairness

- nearly all notions found in the literature are too strong
- by analysing this we built a taxonomy of fairness notions



Justness



once a non-blocking transition is enabled that stems from a set of parallel components, one (or more) of these components will eventually partake in a transition.

- clearly, it is a completeness criterion as well
- it is not entirely compositional, but that is intended
- **Hypothesis/Conjecture:**
justness can be assumed for all distributed systems
(in contrast to fairness notions)

How to Formalise Justness



- although the idea is simple, its formalisation is not
 - what is a component
 - how to encode it in transition systems
 - which components partake in an action
- a co-inductive definition for CCS

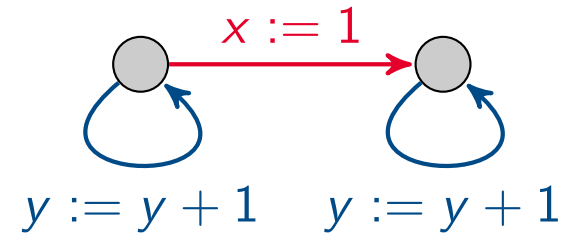
B-justness, for $B \subseteq Act$, is the largest family of predicates on the paths in the LTS of CCS such that

- a finite *B-just* path ends in a state that admits actions from B only
- a *B-just* path of a process $P|Q$ can be decomposed into a *C-just* path of P and a *D-just* path of Q , for some $C, D \subseteq B$ such that $\tau \in B \vee C \cap \bar{D} = \emptyset$
- a *B-just* path of $P \setminus L$ can be decomposed into a $B \cup L \cup \bar{L}$ -just path of P
- a *B-just* path of $P[f]$ can be decomposed into an $f^{-1}(B)$ -just path of P
- and each suffix of a *B-just* path is *B-just*.

How to formalise Justness

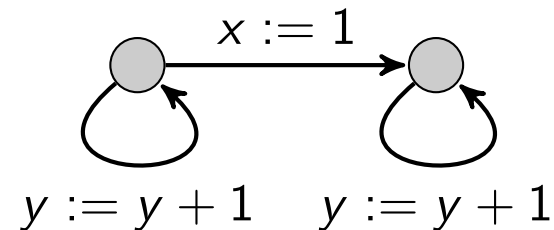
- Component Labelled Transition Systems (CLTS)

$x := 1$ || **loop** $y := y + 1$ **forever**



- justness allows to distinguish this from

```
loop
  choose
    if True then  $y := y + 1$  fi
    if  $x = 0$  then  $x := 1$  fi
  end
forever
```

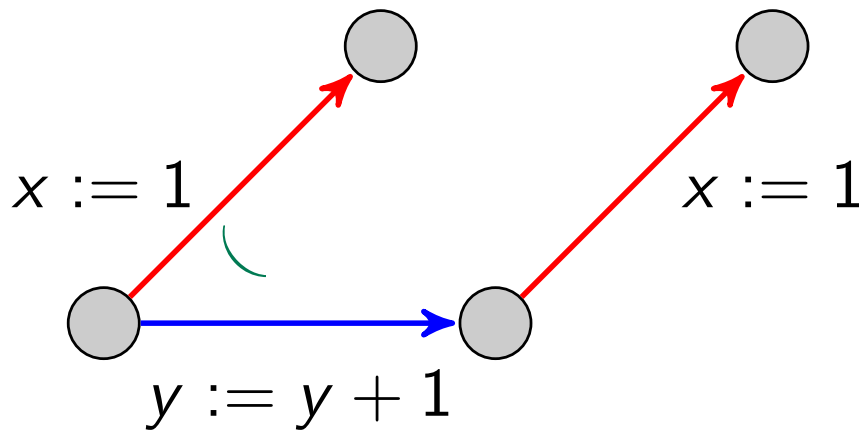


Component Labelled Transition System



A *component-labelled transition system* (CLTS) is a tuple $(S, \text{Tr}, \text{src}, \text{trgt}, \ell, B, \text{comp})$ with S and Tr sets (of *states* and *transitions*), $\text{src}, \text{trgt} : \text{Tr} \rightarrow S$, $\ell : \text{Tr} \rightarrow \text{Act}$ for a set of actions Act , $B \subseteq \text{Act}$ a set of *blocking* actions, and $\text{comp} : \text{Tr} \rightarrow \mathcal{P}(\mathcal{C}) \setminus \emptyset$ for some set of components \mathcal{C} , such that:

if $t, v \in \text{Tr}$ with $\text{src}(t) = \text{src}(v)$ and $\text{comp}(t) \cap \text{comp}(v) = \emptyset$, then there is a $u \in \text{Tr}$ with $\text{src}(u) = \text{trgt}(v)$, $\ell(u) = \ell(t)$ and $\text{comp}(u) = \text{comp}(t)$.



Justness on CLTSs



Two transitions $t, u \in \text{Tr}$ are *concurrent*, notation $t \smile u$, if

$$\text{comp}(t) \cap \text{comp}(u) = \emptyset$$

A path π in an CLTS is *just*

if for each transition $t \in \text{Tr}_{\neg B}$ with $s := \text{src}(t) \in \pi$,
a transition u occurs in π past the occurrence of s ,
such that $t \not\smile u$.

Results



- both notions of justness coincide (for CCS)
- one colouring is not sufficient as there may be affected and necessary components
 - process algebra with signals / Petri Nets with Read Arcs
 - mechanisms with broadcast mechanisms
 - ...
- CLTSs can be “expanded” to two colourings

Examples



- process algebras with signals / Petri Nets with read arcs
 - assume a traffic light,
 - as the light does not change state when a car crosses
 - the traffic light should not be “blocked” while a second car crosses
 - reading values concurrently
 - affected components (car) cannot act without necessary ones
- mechanisms with broadcast
 - broadcast sender is both affected and necessary
 - recipients are
- in general affected and necessary components are independent and can be used to define the concurrency relation which becomes asymmetric

The Good, the Bad, the Ugly



- **The Good**

- justness seems to be the fundamental “fairness” property that can/should be assumed for any distributed system
- it probably can be defined for any formalism of concurrency

- **The Bad**

- although its characterisation is fairly simple, its formal definition is not
- or at least not yet

- **~~The Ugly~~ Exciting**

- new proof theory needs to be developed



Thank you

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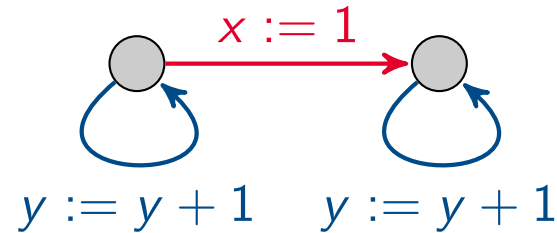
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Updating Bisimulation

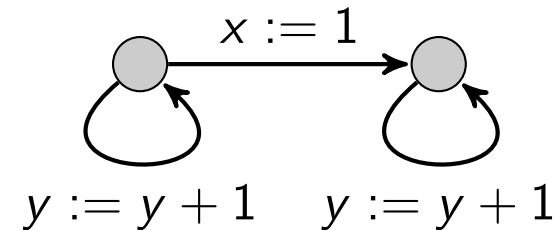
- Component Labelled Transition Systems with Concurrency (CLTS)

$x := 1 \parallel \text{loop } y := y + 1 \text{ forever}$



- justness allows to distinguish this from

```
loop
  choose
    if True then  $y := y + 1$  fi
    if  $x = 0$  then  $x := 1$  fi
  end
forever
```



- however, both systems are bisimilar
a new theory needs to be developed

Bisimulation using Components

Can we build an equivalence \approx_{cp} that meets our needs?

